

Lab 6: the big picture

- You add
 - YKQCreate()
 - YKQPend()
 - YKQPost()
- You modify tick handler so that it posts one message to a queue each time it runs. (The queue is emptied by a task.)
- Higher priority task can hog CPU for 5-cycle intervals, letting messages queue up.
 - Execution of high priority task triggered by any key (keypress ISR sets flag)



425 Lab 6.1

```

/*
File: lab6app.c
Description: Application code for ECEn 425 lab 6 (Message queues)
*/

#include "clib.h"           /* contains kernel definitions */
#include "yakit.h"         /* contains user's definitions */
#include "lab6defs.h"

#define TASK_STACK_SIZE 512 /* stack size in words */
#define MSGQSIZE 10

struct msg MsgArray[MSGARRAYSIZE]; /* buffers for message content */

int ATaskStk[TASK_STACK_SIZE]; /* a stack for each task */
int BTaskStk[TASK_STACK_SIZE];
int STaskStk[TASK_STACK_SIZE];

int GlobalFlag;

void *MsgQ[MSGQSIZE]; /* space for message queue */
YKQ *MsgQPtr; /* global handle for queue */
    
```

/* File: lab6defs.h */
 #define MSGARRAYSIZE 20
 struct msg
 {
 int tick;
 int data;
 };

Big enough that queue should not overflow.



425 Lab 6.2

```

void ATask(void) /* empties msg queue */
{
    struct msg *tmp;
    int min, max, count;

    min = 100;
    max = 0;
    count = 0;

    while (1)
    { /* get next msg */
        tmp = (struct msg *) YKQPend(MsgQPtr);

        /* check sequence count in msg;
        were msgs dropped? */
        if (tmp->tick != count+1)
        {
            printf("Dropped msgs: tick ", 21);
            if (tmp->tick - (count+1) > 1) {
                printf(count+1);
                printfChar("-");
                printf(tmp->tick-1);
                printfNewLine();
            }
            else {
                printf(tmp->tick-1);
                printfNewLine();
            }
        }

        /* update sequence count */
        count = tmp->tick;

        /* process data; update statistics
        for this sample */
        if (tmp->data < min)
            min = tmp->data;
        if (tmp->data > max)
            max = tmp->data;

        /* output min, max, tick values */
        printf("Ticks: ", 7);
        printf(count);
        printf(" ", 1);
        printf("Min: ", 5);
        printf(min);
        printf(" ", 1);
        printf("Max: ", 5);
        printf(max);
        printfNewLine();
    }
}
    
```

This task empties queue of messages generated by the tick handler, one message per tick.



425 Lab 6.3

BTask is a CPU hog that keeps ATask from running. Its busy bursts are triggered by the press of any key and last for five clock ticks each.

```

void BTask(void) /* saturates CPU for 5 ticks */
{
    int busycount, curval, flag, chcount;
    unsigned tickNum;

    curval = 1001;
    chcount = 0;
    while (1)
    {
        YKDelayTask(2);
        if (GlobalFlag == 1)
        { /* flag set - loop for 5 ticks */
            YKEnterMutex();
            busycount = YKTickNum;
            YKExitMutex();
        }
    }
}

while (1) {
    YKEnterMutex();
    tickNum = YKTickNum;
    YKExitMutex();

    if (tickNum == busycount + 5) break;
    flag = 0;
    curval += 2; /* evaluate next number */
    for (j = 3; (j) < curval; j += 2) {
        if (curval % j == 0) {
            flag = 1;
            break;
        }
    }
    if (!flag) {
        printfChar(" "); /* output marker for each */
        if (++chcount > 75) {
            printfNewLine();
            chcount = 0;
        }
    }
    printfNewLine();
    chcount = 0;
    GlobalFlag = 0; /* clear flag */
}
}
    
```



425 Lab 6.4

```

void STask(void) /* tracks statistics */
{
    unsigned max, switchCount, idleCount;
    int tmp;

    YKDelayTask(1);
    printfString("Welcome to the YAK kernel\n");
    printfString("Determining CPU capacity\n");
    YKDelayTask(1);
    YKIdleCount = 0;
    YKDelayTask(5);
    max = YKIdleCount / 25;
    YKIdleCount = 0;
    YKNewTask(BTask, (void *) &BTaskStk[TASK_STACK_SIZE], 10);
    YKNewTask(ATask, (void *) &ATaskStk[TASK_STACK_SIZE], 20);
    while (1) {
        YKDelayTask(20);
        YKEnterMutex();
        switchCount = YKCtxSwCount;
        idleCount = YKIdleCount;
        YKExitMutex();
        printfString("<<<<< Context switches: ");
        printf(int(switchCount));
        printfString(", CPU usage: ");
        tmp = (int) (idleCount/max);
        printf("100-tmp);
        printfString("%>>>>>\n");
        YKEnterMutex();
        YKCtxSwCount = 0;
        YKIdleCount = 0;
        YKExitMutex();
    }
}
    
```

The stat task, just like lab 5. Starts tasks A and B. Prints statistics every 20 ticks.



425 Lab 6.5

```

void main(void)
{
    YKInitialize();

    /* create queue, at least one user task, etc. */
    GlobalFlag = 0;
    MsgQPtr = YKQCreate(MsgQ, MSGQSIZE);
    YKNewTask(STask, (void *) &STaskStk[TASK_STACK_SIZE], 30);

    YKRun();
}
    
```



425 Lab 6.6

Lab 6: Changes to interrupt handlers

- Keypress handler
 - No longer generates output – just sets **GlobalFlag** to 1.
- Reset handler
 - No modification from previous labs.
- User code tick handler
 - No longer generates "--TICK X--" output
 - Puts a message into the message queue each time it runs.
 - You are given the code for this. (See next slide.)

```

/* File: lab6inth.c
Description: Sample interrupt handler code for EE 425 lab 6 (Message queues) */

#include "lab6defs.h"
#include "yakk.h"
#include "clib.h"

extern YKQ *MsgQPtr;
extern struct msg MsgArray[];
extern int GlobalFlag;

void myreset(void) {
    exit(0);
}

void mykeybrd(void) {
    GlobalFlag = 1;
}

void mytick(void) {
    static int next = 0;
    static int data = 0;

    /* create a message with tick (sequence #) and pseudo-random data */
    MsgArray[next].tick = YKTickNum;
    data = (data * 89) % 100;
    MsgArray[next].data = data;
    if (YKQPost(MsgQPtr, (void *) &MsgArray[next]) == 0)
        printf("TickISR: queue overflow! \n");
    else if (++next >= MSGARRAYSIZE)
        next = 0;
}
    
```

```

/* File: lab6defs.h */
#define MSGARRAYSIZE 20

struct msg
{
    int tick;
    int data;
};
    
```

```

Welcome to the YAK kernel
Determining CPU capacity
Ticks: 1  Min: 80 Max: 89
Ticks: 2  Min: 78 Max: 89
Ticks: 3  Min: 67 Max: 89
Ticks: 4  Min: 56 Max: 89
Ticks: 5  Min: 45 Max: 89
Ticks: 6  Min: 34 Max: 89
Ticks: 7  Min: 23 Max: 89
Ticks: 8  Min: 12 Max: 89
Ticks: 9  Min: 1 Max: 89
Ticks: 10 Min: 1 Max: 90
Ticks: 11 Min: 1 Max: 90
Ticks: 12 Min: 1 Max: 90
Ticks: 13 Min: 1 Max: 90
Ticks: 14 Min: 1 Max: 90
Ticks: 15 Min: 1 Max: 90
Ticks: 16 Min: 1 Max: 90
Ticks: 17 Min: 1 Max: 90
Ticks: 18 Min: 1 Max: 90
Ticks: 19 Min: 1 Max: 91
Ticks: 20 Min: 1 Max: 91
-----
Ticks: 21 Min: 1 Max: 91
Ticks: 22 Min: 1 Max: 91
Ticks: 23 Min: 1 Max: 91
Ticks: 24 Min: 1 Max: 91
Ticks: 25 Min: 1 Max: 91
Ticks: 26 Min: 1 Max: 91
Ticks: 27 Min: 1 Max: 91
<<<<< Contest switches: 62, CPU usage: 11% >>>>>
Ticks: 28 Min: 1 Max: 92
Ticks: 29 Min: 1 Max: 92
    
```

Sample output:
default tick rate

- Requirements at default tick rate:**
- No messages dropped
 - Normal Stat task output

Key is pressed,
Keypress ISR sets GlobalFlag,
BTask hogs CPU for 5 tick intervals

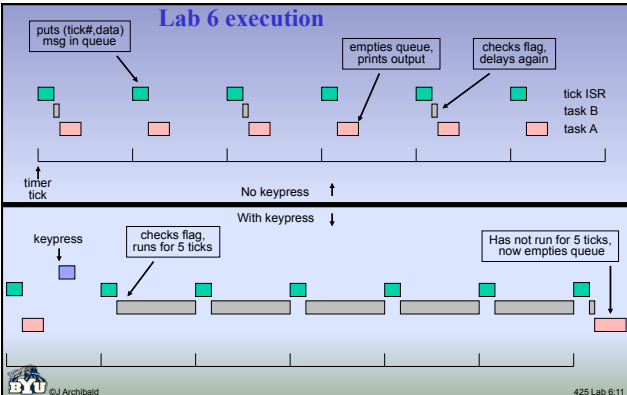
```

Ticks: 175  Min: 0 Max: 99
Ticks: 176  Min: 0 Max: 99
Ticks: 177  Min: 0 TickISR: queue overflow!
Max: 99
! Dropped msgs: tick 178
Ticks: 179  Min: 0 Max: TickISR: queue overflow!
99
! Dropped msgs: tick 180
Ticks: 181  Min: 0 Max: TickISR: queue overflow!
99
! Dropped msgs: tick 182
Ticks: 183  Min: 0 Max: 99
Ticks: 184  Min: 0 Max: 99
TickISR: queue overflow!
! Dropped msgs: tick 185
Ticks: 186  Min: 0 Max: 99
Ticks: 187  Min: 0 Max: TickISR: queue overflow!
99
! Dropped msgs: tick 188
Ticks: 189  Min: 0 Max: TickISR: queue overflow!
99
! Dropped msgs: tick 190
Ticks: 191  Min: 0 Max: 99
Ticks: 192  Min: 0 Max: 99
Ticks: 193  Min: 0 TickISR: queue overflow!
Max: 99
! Dropped msgs: tick 194
Ticks: 195  Min: 0 Max: TickISR: queue overflow!
99
! Dropped msgs: tick 196
    
```

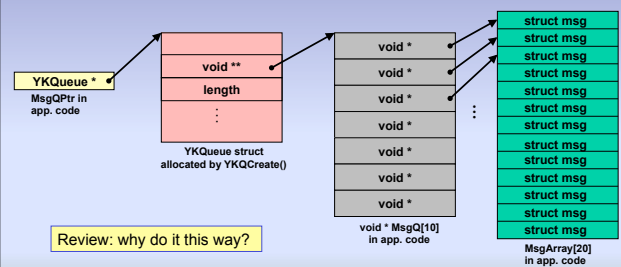
Sample output:
750 instr/tick

- Requirements at 750 instr/tick:**
- Code does not crash
 - Task A still gets *some* entries from queue if CPU hog not running, but some entries may be dropped.
 - May not see *any* stat task output

Lab 6 execution



Lab 6 data structures for queue, messages



YAK functions for Lab 6

`YKQ *YKQCreate(void **start, unsigned size)`

- Initializes data structure used to maintain queue, returns pointer to it
- Parameters:
 - **start**: specifies base address of the queue itself, an array of void pointers
 - **size**: specifies number of entries in queue (size of the array)
- Return value:
 - pointer to initialized queue management struct allocated for this new queue
- YKQ is typedef defined in kernel header file; defines struct that records
 - values to manage queue: base address, queue size, head + tail indices, etc.
- Must be called exactly once per message queue, ideally in `main()`



425 Lab 6.13

YAK functions for Lab 6

`void *YKQPend(YKQ *queue)`

- If message queue is not empty, removes and returns the oldest message.
- If message queue is empty, calling task is suspended by the kernel until a message is placed in queue.
- Parameter:
 - **queue**: specific queue to use (pointer to queue management struct)
- Called only by tasks, never by interrupt code.



425 Lab 6.14

YAK functions for Lab 6

`int YKQPost(YKQ *queue, void *msg)`

- Inserts a new message into message queue
- Parameters:
 - **queue**: specific queue to use (pointer to queue management struct)
 - **msg**: pointer value to insert
- Return value:
 - 1 if queue is not full and message insertion was successful.
 - 0 if queue is full and message was not inserted.
- If one or more blocked tasks are waiting for a message from this queue, the highest priority waiting task is unblocked when new message is inserted
- This function may be called from *both* task and interrupt code.
 - If called from interrupt code, *it must not call the scheduler.*



425 Lab 6.15